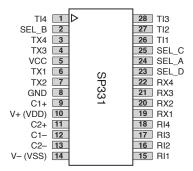
### Programmable Dual RS-232/RS-485Transceiver

p://www.kttic.com

#### FEATURES

- +5V Only Operation
- Software Programmable RS-232 or RS-485 Selection
- Four RS-232 Transceivers in RS-232 Mode
- Two RS-485 Full-Duplex Transceivers in RS-485 Mode
- Two RS-232 Transceivers and One RS-485 Transceiver in Dual Mode
- Self-Testing Loopback Mode
- Full Driver Tri-State (Hi-Z) Control
- Ideal for RS-232 to RS-485 conversion



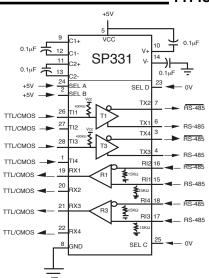
Now Available in Lead Free Packaging

#### **DESCRIPTION**

**SP331** 

The SP331 is a programmable RS-232 and/or RS-485 transceiver IC. The SP331 contains four drivers and four receivers when selected in RS-232 mode; and two drivers and two receivers when selected in RS-485 mode. The SP331 also contains a dual mode which has two RS-232 drivers/receivers plus one differential RS-485 driver/receiver.

The RS-232 transceivers can typically operate at 230kbps while adhering to the RS-232 specifications. The RS-485 transceivers can operate up to 10Mbps while adhering to the RS-485 specifications. The SP331 includes a self-test loopback mode where the driver outputs are internally configured to the receiver inputs. This allows for easy diagnostic serial port testing without using an external loopback plug. The RS-232 and RS-485 drivers can be disabled (High-Z output) by controlling a set of four select pins.



#### TYPICAL APPLICATION CIRCUITS

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These are stress ratings only and functional operation of the device at these ratings or any other above those indicated in the operation sections of the specifications below is not implied. Exposure to absolute maximum rating conditions for extended periods of time may affect reliability.

V <sub>cc</sub>	+7V
Storage Temperature65°C	
Power Dissipation	
28-pin Plastic DIP	1000mW
28-pin Plastic SOIC	1000mW

Package Derating:	
28-pin Plastic DIP	
Ø <sub>JA</sub>	40°C/W
28-pin Plastic SOIC	
Ø <sub>JA</sub>	40°C/W

#### **ELECTRICAL CHARACTERISTICS**

	MIN.	TYP.	MAX.	UNITS	CONDITIONS
LOGIC INPUTS					
V <sub>IL</sub>			0.8	Volts	
V <sub>IH</sub>	2.0			Volts	
LOGIC OUTPUTS					
V <sub>OL</sub>			0.4	Volts	I <sub>OUT</sub> = -3.2mA
V <sub>OH</sub>	2.4			Volts	$I_{OUT} = 1.0 \text{mA}$
RS-232 DRIVER					
DC Characteristics					
HIGH Level Output	+5.0		+15	Volts	R <sub>L</sub> =3kΩ, V <sub>IN</sub> =0.8V
LOW Level Output	-15.0		-5.0	Volts	R <sub>L</sub> =3kΩ, V <sub>IN</sub> =2.0V
Open Circuit Voltage	-15		+15	Volts	
Short Circuit Current			±100	mA	V <sub>OUT</sub> = 0V
Power Off Impedance	300			Ω	$V_{cc} = 0V, V_{out} = \pm 2.0V$
AC Characteristics			00		
Slew Rate			30	V/μs	$R_L=3k\Omega$ , $C_L=50pF$
Transition Time			1.5		V <sub>CC</sub> = +5.0V, T <sub>A</sub> @ +25°C R <sub>I</sub> =3kΩ, C <sub>I</sub> =2500pF ;
Transition Time			1.5	μS	between $\pm 3V$ , $T_A @ \pm 25^{\circ}C$
Maximum Data Rate	120	235		kbps	$R_1 = 3k\Omega, C_1 = 2500pF$
Propagation Delay	120	200		hope	
t <sub>PHL</sub>		2	8	μS	Measured from 1.5V of V <sub>IN</sub>
t <sub>PLH</sub>		2	8	μS	to 50% of $V_{OUT}$ ; $R_L=3k\Omega^{IN}$
RS-232 RECEIVER					
DC Characteristics					
HIGH Threshold		1.7	3.0	Volts	
LOW Threshold	0.8	1.2		Volts	
Receiver Open Circuit Bias			+2.0	Volts	
Input Impedance	3	5	7	kΩ	$V_{IN} = +15V \text{ to } -15V$
AC Characteristics					
Maximum Data Rate	120	235		kbps	
Propagation Delay		0.05			
t <sub>PHL</sub>		0.25 0.25	1	μS	Measured from 50% of V <sub>IN</sub>
		0.25	1	μS	to 1.5V of V <sub>OUT</sub> .
RS-485 DRIVER					
DC Characteristics				Valta	
Open Circuit Voltage	15		6.0	Volts	
Differential Output	1.5		5.0	Volts	$R_L=54\Omega, C_L=50pF$

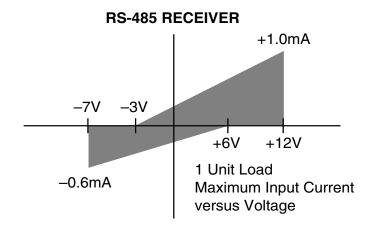
Typically 25°C @ Vcc = +5V unless otherwise noted.

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## KTTC <u>http://www.kttic.ccup</u>rical characteristics

Typically 25°C @ Vcc = +5V unl					
	MIN.	TYP.	MAX.	UNITS	CONDITIONS
RS-485 DRIVER Balance Common-Mode Output Output Current Short Circuit Current	28.0		±0.2 3.0 ±250	Volts Volts mA mA	IV <sub>7</sub> I - IV <sub>7</sub> I R <sub>L</sub> =54Ω Terminated in −7V to +10V
AC Characteristics Maximum Data Rate Output Transition Time Propagation Delay t <sub>PHL</sub>	10	30 80	50 120	Mbps ns ns	$R_L=54\Omega$ Rise/fall time, 10%–90% See Figures 2 & 4 $R_{DIFF}=54\Omega$ , $C_{L1}=C_{L2}=100$ pF
t <sub>PLH</sub> Driver Output Skew		80 10	120 20	ns ns	$R_{DIFF}^{DIFF}$ =54 $\Omega$ , $C_{L1}^{L1}$ = $C_{L2}^{L2}$ =100pF per Figure 4, $t_{SKEW}$ = I $t_{DPLH}$ - $t_{DPHL}$ I
RS-485 RECEIVER <u>DC Characteristics</u> Inputs Common Mode Range Receiver Sensitivity Input Impedance <u>AC Characteristics</u> Maximum Data Rate Propagation Delay <sup>t</sup> <sub>PHL</sub> t <sub>PLH</sub> Differential Receiver Skew	-7.0 12 10	±0.2 15 130 130 10	+12.0 ±0.3 200 200 200	Volts Volts kΩ Mbps ns ns ns	$\begin{split} -7V &\leq V_{CM} \leq +12V \\ -7V &\leq V_{CM} \leq +12V \end{split}$ See Figures 2 & 6 R_{DIFF} = 54\Omega, C_{L1} = C_{L2} = 100 \text{pF} \\ R_{DIFF} = 54\Omega, C_{L1} = C_{L2} = 100 \text{pF} \\ t_{SKEW} &= 1 t_{PLH} - t_{PHL} 1; R_{DIFF} = 54\Omega, \\ C_{L1} = C_{L2} = 100 \text{pF} \end{split}
ENABLE TIMING RS-485 Driver Enable Time Enable to Low Enable to High Disable Time Disable From Low Disable From High	K.	90 90 80 80	150 150 120 120	ns ns ns ns	See Figures 3 & 5 $C_L=15pF$ , $S_1$ Closed $C_L=15pF$ , $S_2$ Closed See Figures 3 & 5 $C_L=15pF$ , $S_1$ Closed $C_L=15pF$ , $S_2$ Closed
POWER REQUIREMENTS Supply Voltage V <sub>CC</sub> Supply Current I <sub>CC</sub> No Load (T <sub>x</sub> Disabled) No Load (RS-232 Mode) No Load (RS-485 Mode)	+4.75	10 15 7	+5.25 15 30 20	Volts mA mA mA	SEL_A ➡ SEL_D = "0001" SEL_A ➡ SEL_D = "0000" SEL_A ➡ SEL_D = "1100"
ENVIRONMENTAL Operating Temperature Commercial (C) Industrial (E) Storage Temperature	0 40 65		+70 +85 +150	ى ى گ	

## KTTHECEIVE FINTERDORF / RAY WW. Kttic.com



#### **TEST CIRCUITS**

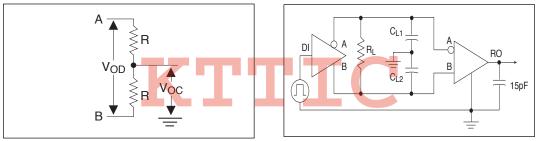
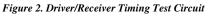


Figure 1. Driver DC Test Load Circuit



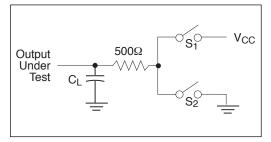
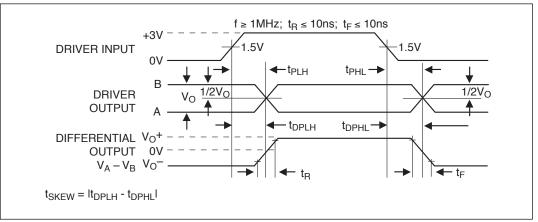
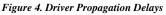


Figure 3. Driver Timing Test Load #2 Circuit

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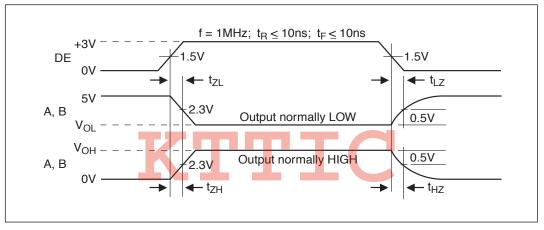


Figure 5. Driver Enable and Disable Times

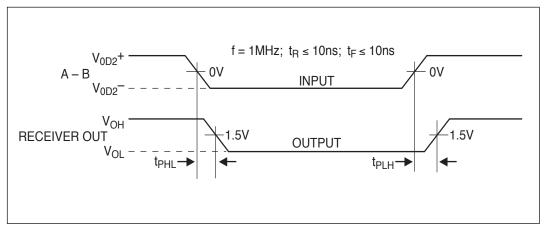


Figure 6. Receiver Propagation Delays

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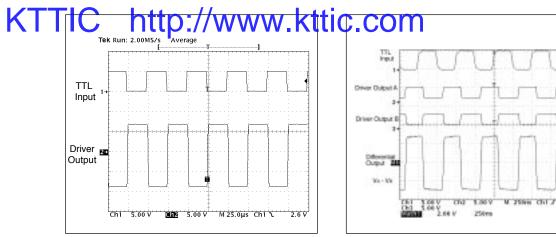


Figure 7. Typical RS-232 Driver Output

Figure 8. Typical RS-485 Driver Output

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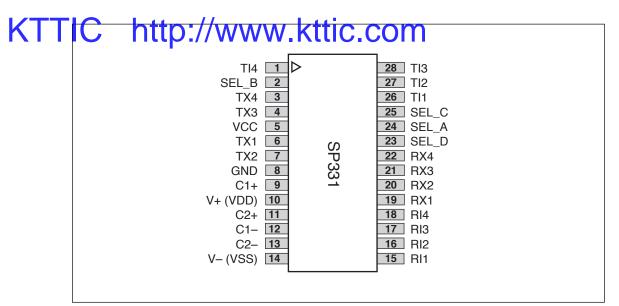


Figure 9. SP331 Pinout

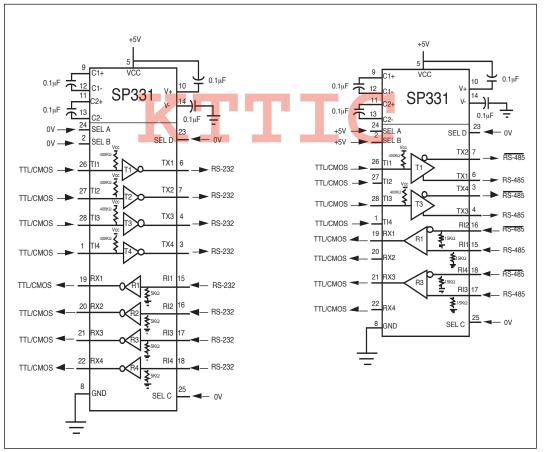


Figure 10. Typical Operating Circuit

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## KTTFUNCTION TATE FOR SELACY FINK TTIC.COM

A	B	<u>C</u>	D	MODE	<b>FUNCTION</b>
0	0	0	0	RS-232	All four RS-232 drivers active
0	0	0	1	RS-232	All four RS-232 drivers tri-state
0	0	1	0	RS-232	All four RS-232 drivers tri-state
0	0	1	1	RS-232	RS-232 (4ch) Loopback
0	1	0	0	RS-232/RS-485	T1 and T2 active RS-232; T3 tri-state RS-485
0	1	0	1	RS-232/RS-485	T1 and T2 tri-state RS-232; T3 active RS-485
0	1	1	0	RS-232/RS-485	T1 and T2 active RS-232; T3 tri-state RS-485
0	1	1	1	RS-232/RS-485	RS-232 (2ch) / RS-485 (1ch) Loopback
1	0	0	0	RS-485/RS-232	T1 active RS-485; T3 and T4 active RS-232
1	0	0	1	RS-485/RS-232	T1 tr-state RS-485; T3 active RS-232; T4 active RS232
1	0	1	0	RS-485/RS-232	All RS-485 and RS-232 drivers tri-state
1	0	1	1	RS-485/RS-232	RS-485 (1ch) / RS-232 (2ch) Loopback
1	1	0	0	RS-485	T1 and T3 active RS-485
1	1	0	1	RS-485	T1 tri-state RS-485; T3 active RS-485
1	1	1	0	RS-485	T1 active RS-485; T3 tri-state RS-485
1	1	1	1	RS-485	RS-485 (2ch) Loopback

Table 1. Mode Function Table. (Refer to Control Logic Confirmations for Block Diagrams)

#### THEORY OF OPERATION

The **SP331** is made up of four separate circuit blocks — the charge pump, drivers, receivers, and decoder. Each of these circuit blocks is described in more detail below.

#### Charge–Pump

The charge pump is a **Sipex**-patented design (U.S. 5,306,954) and uses a unique approach compared to older less efficient designs. The charge pump still requires four external capacitors, but uses a four-phase voltage shifting technique to attain symmetrical 10V power supplies. *Figure* 15(a) shows the waveform found on the positive side of capcitor C2, and *Figure* 15(b) shows the negative side of capcitor C2. There is a free-running oscillator that controls the four phases of the voltage shifting. A description of each phase follows.

#### Phase 1

—  $V_{SS}$  charge storage —During this phase of the clock cycle, the positive side of capacitors  $C_1$  and  $C_2$  are initially charged to +5V.  $C_1^+$  is then switched to ground and charge on  $C_1^-$  is transferred to  $C_2^-$ . Since  $C_2^+$  is connected to +5V, the voltage potential across capacitor  $C_2$  is now 10V.

#### Phase 2

-  $V_{ss}$  transfer - Phase two of the clock connects the negative terminal of C<sub>2</sub> to the V<sub>ss</sub> storage capacitor and the positive terminal of C<sub>2</sub> to ground, and transfers the generated -l0V to C<sub>3</sub>. Simultaneously, the positive side of capacitor C<sub>1</sub> is switched to +5V and the negative side is connected to ground.

#### Phase 3

 $-V_{DD}$  charge storage — The third phase of the clock is identical to the first phase — the charge transferred in C<sub>1</sub> produces -5V in the negative terminal of C<sub>1</sub>, which is applied to the negative side of capacitor C<sub>2</sub>. Since C<sub>2</sub><sup>+</sup> is at +5V, the voltage potential across C<sub>2</sub> is IOV.

#### Phase 4

—  $V_{DD}$  transfer — The fourth phase of the clock connects the negative terminal of  $C_2$  to ground and transfers the generated 10V across  $C_2$  to  $C_4$ , the  $V_{DD}$  storage capacitor. Again,

KTTIC http://www.ktticsimperfuly with this, the positive side of

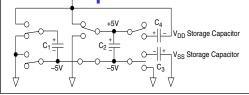


Figure 11. Charge Pump Phase 1.

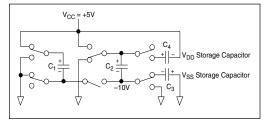


Figure 12. Charge Pump Phase 2.

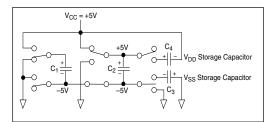


Figure 13. Charge Pump Phase 3.

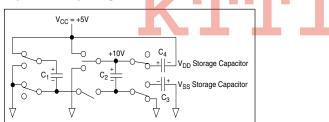


Figure 14. Charge Pump Phase 4.

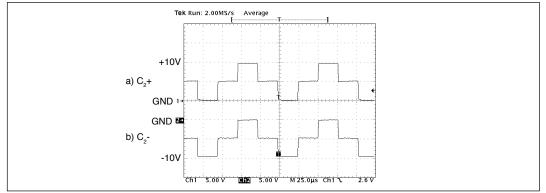


Figure 15. Charge Pump Waveforms

since the positive side of capacitor  $C_1$  is switched to +5V and the negative side is connected to ground, and the cycle begins again.

Since both V+ and V<sup>-</sup> are separately generated from V<sub>CC</sub> in a no–load condition, V+ and V<sup>-</sup> will be symmetrical. Older charge pump approaches that generate V<sup>-</sup> from V+ will show a decrease in the magnitude of V<sup>-</sup> compared to V+ due to the inherent inefficiencies in the design.

The clock rate for the charge pump typically operates at 15kHz. The external capacitors must be  $0.1\mu$ F with a 16V breakdown rating.

#### **External Power Supplies**

For applications that do not require +5V only, external supplies can be applied at the V+ and V<sup>-</sup> pins. The value of the external supply voltages must be no greater than  $\pm 10V$ . The current drain for the  $\pm 10V$  supplies is used for RS-232. For the RS-232 driver the current requirement will be 3.5mA per driver. The external power supplies should provide a power supply sequence of :+10V, then +5V, followed by -10V.

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The SP331 has four independent RS-232 singleended drivers and two differential RS-485 drivers. Control for the mode selection is done via a four-bit control word. The drivers are prearranged such that for each mode of operation the relative position and functionality of the drivers are set up to accommodate the selected interface mode. As the mode of the drivers is changed, the electrical characteristics will change to support the requirements of clock, data, and control line signal levels. Unused driver inputs can be left floating; however, to ensure a desired state with no input signal, pull-up resistors to +5V or pull-down resistors to ground are suggested. Since the driver inputs are both TTL or CMOS compatible, any value resistor less than  $100k\Omega$  will suffice.

When in RS-232 mode, the single-ended RS-232 drivers produce compliant RS-232E and ITU V.28 signals. Each of the four drivers output single-ended bipolar signals in access of  $\pm 5$ V with a full load of 3k $\Omega$  and 2500pF applied as specified. These drivers can also operate at least 120kbps.

When programmed to RS-485 mode, the differential RS-485 drivers produce complaint RS-485 signals. Each RS-485 driver outputs a unipolar signal on each output pin with a magnitude of at least 1.5V while loaded with a worst case of 54 $\Omega$  between the driver's two output pins. The signal levels and drive capability of the RS-485 drivers allow the drivers to also comply with RS-422 levels. The transmission rate for the differential drivers is 10Mbps.

#### Receivers

The **SP331** has four single-ended receivers when programmed for RS-232 mode and two differential receivers when programmed for RS-485 mode.

Control for the mode selection is done via a 4bit control word, as in the drivers. As the operating mode of the receivers is changed, the electrical characteristics will change to support the requirements of the appropriate serial standard. Unused receiver inputs can be left floating

http://www.ktti Cvittor and g oscillation. To ensure a desired state of the receiver output, a pull–up resistor of 100k $\Omega$  to +5V should be connected to the inverting input for a logic low, or the non–inverting input for a logic high. For single-ended receivers, a pull–down resistor to ground of 5k $\Omega$  is internally connected, which will ensure a logic high output.

The RS-232 receiver has a single–ended input with a threshold of 0.8V to 2.4V. The RS-232 receiver has an operating voltage range of  $\pm 15V$ and can receive signals up to 120kbps. RS-232 receivers are used in RS-232 mode for all signal types include data, clock, and control lines of the RS-232 serial port.

The differential RS-485 receiver has an input impedance of  $15k\Omega$  and a differential threshold of  $\pm 200$ mV. Since the characteristics of an RS-422 receiver are actually subsets of RS-485, the receivers for RS-422 requirements are identical to the RS-485 receivers. All of the differential receivers can receive data up to 10Mbps.

#### Select Mode Pins

Similar to our SP500 family of multiprotocol products, the SP331 has the ability to change the configuration of the drivers and receivers via a 4-bit switch. Referring to *Table 1*; RS-232 mode, RS-485 mode, or two different combinations of RS-232/RS-485 can be configured using the SEL\_A and SEL\_B pins. The drivers can be put into tri-state mode by using the SEL\_C and SEL\_D pins. All receivers remain active during any tri-state condition of the drivers.

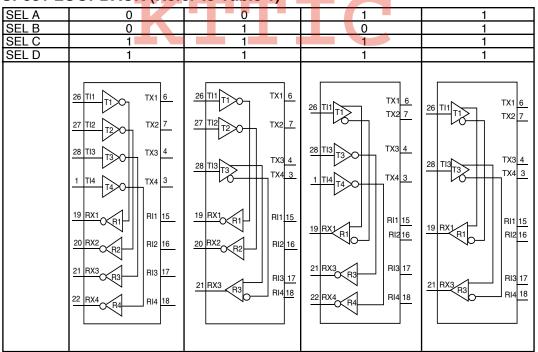
#### Loopback Mode

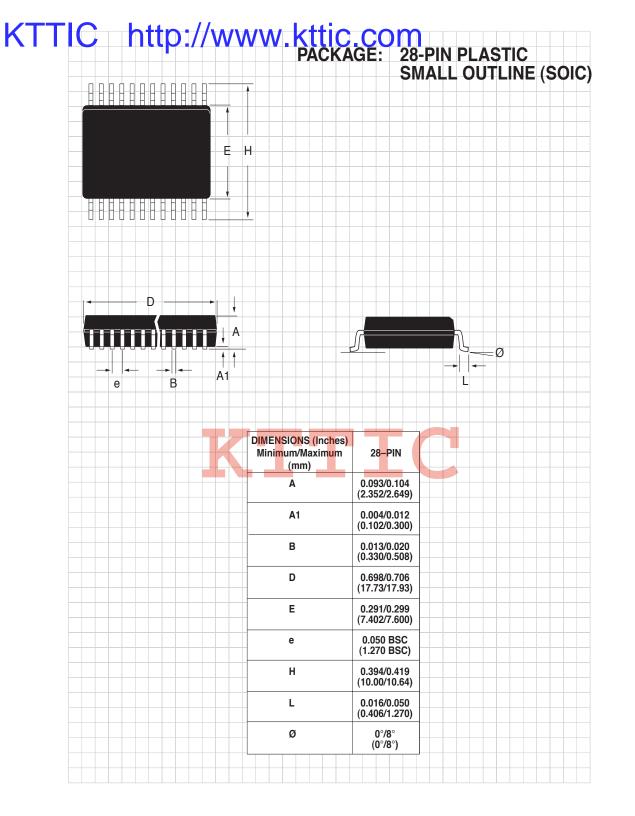
Loopback is invoked by asserting "xx11" into the select pins. In RS-232/RS-485 or RS-485/ RS-232 loopback mode, the RS-232 driver outputs loop back into the RS-232 receiver inputs and the RS-485 differential driver loops back into the RS-485 receiver. During loopback, the driver outputs and receiver inputs are disconnected from the outside world. The driver outputs are in tri-state and the receiver inputs are disabled. The input impedance of the receivers during loopback is approximately  $15k\Omega$  to ground.

## KTT SP331 CONTROL/LOCIC CONFICURATION (Refer to Table 1)

SEL A	0	0	0	0	0	0	1	1	1	1	1	1
SEL B	0	0	0	1	1	1	0	0	0	1	1	1
SEL C	0	0	1	0	0	1	0	0	1	0	0	1
SEL D	0	1	0	0	1	0	0	1	0	0	1	0
	26 TI1 27 TI2 28 TI3 1 TI4 19 RX1 20 RX2 21 RX3 22 RX4		X1 6   TX2 7   X3 4   TX4 3   RI1 15   RI2 16   RI3 17   RI4 18	26 T11 27 T12 28 T13 19 RX1 20 RX2 21 RX3		TX1 6 TX2 7 TX3 4 TX4 3 RI1 15 RI2 16 RI3 17 RI4 18	26 T11 28 T13 1 T14 19 RX1 21 RX3 22 RX4		TX1 6 TX2 7 TX3 4 TX4 3 RI1 15 RI2 16 RI3 17 RI4 18	26 TI1 28 TI3 19 RX1 21 RX3		TX1 6 TX2 7 TX3 4 TX4 3 RI1 15 RI2 16 RI3 17 RI4 18

#### SP331 LOOPBACK (Refer to Table 1)





ТΤ		http://www.enkitineo.rowonon	
	Model	Temperature Range	Package Types
	SP331CT		
	SP331CT/TR.	0°C to +70°C	
	SP331ET		
	SP331ET/TR.	-40°C to +85°C	

Available in lead free packaging. To order add "-L" suffix to part number.

Example: SP331ET/TR = standard; SP331ET-L/TR = lead free

/TR = Tape and Reel

Pack quantity is 1,500 for WSIOC.

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